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# The Whitham hierarchies: reductions and hodograph solutions 

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#### Abstract

A general scheme for analysing reductions of Whitham hierarchies is presented. It is based on a method for determining the $S$-function by means of a system of first-order partial differential equations. Compatibility systems of differential equations characterizing both reductions and hodograph solutions of Whitham hierarchies are obtained. The method is illustrated by exhibiting solutions of integrable models such as the dispersionless Toda equation (heavenly equation) and the generalized Benney system.


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## 1. Introduction

The study of dispersionless (or quasiclasssical) limits of integrable systems of KdV type and their applications has been an active subject of research for more than 20 years (see for example [1-14]). However, despite the fact that many important developments on the algebraic and geometric aspects of these systems have been made, the theory of their solution methods seems far from being completed. Indeed, only for a few cases [15-17] is the dispersionless limit of the inverse scattering method available and dispersionless versions of ordinary direct methods such as the $\bar{\partial}$-method are not yet fully developed [18].

In [3, 4] Kodama and Gibbons provided a direct method for finding solutions of the dispersionless KP (dKP) equation

$$
\begin{equation*}
\left(u_{t}+3 u u_{x}\right)_{x}=\frac{3}{4} u_{y y} \tag{1}
\end{equation*}
$$

and its associated dKP hierarchy of nonlinear systems. The main ingredient of their method is the use of reductions of the dKP hierarchy formulated in terms of hydrodynamic-type equations. As a consequence, it follows that solutions of the dKP hierarchy turn out to be determined through hodograph equations. Recently, we proposed [19] an alternative direct method for solving the dKP hierarchy from its reductions. It is based on the characterization
of reductions and hodograph solutions of the dKP hierarchy by means of certain systems of first-order partial differential equations.

The aim of this paper is to present a generalization of the method in [19] which applies to the Whitham hierarchies of dispersionless integrable systems. These hierarchies were introduced by Krichever in [7] and contain many interesting dispersionless models such as, for example, the $(2+1)$-dimensional integrable systems

$$
\begin{equation*}
\Phi_{x y}+\left(\mathrm{e}^{\Phi}\right)_{t t}=0 \tag{2}
\end{equation*}
$$

known as the dispersionless Toda (dT) equation (heavenly equation or Boyer-Finley equation [20,21]), and the generalized Benney system [10]

$$
\begin{equation*}
a_{t}+(a v)_{t}=0 \quad v_{t}+v v_{x}+w_{x}=0 \quad w_{y}+a_{x}=0 . \tag{3}
\end{equation*}
$$

In the next section, we review briefly the definition of the Whitham hierarchies (zero genus case) and introduce our main notation conventions. Section 3 deals with the method for characterizing reductions and hodograph solutions of the Whitham hierarchies. To this end, we take advantage of the same scheme as in [19] to introduce reductions through systems of first-order partial differential equations. The main difference with respect to the procedure used in [19] lies in the more involved construction of the $S$-function. As in the study of the dKP hierarchy, we find that the compatibility equations for characterizing diagonal reductions of the Whitham hierarchies are deeply connected with the theory of Combescure transformations of conjugate nets. Finally, section 4 is devoted to illustrating the method with examples of hodograph solutions of (2) and (3).

## 2. The Whitham hierarchy

The $M$ th Whitham hierarchy is related to a family of evolution equations for a set of $M$ functions $z_{\alpha}=z_{\alpha}(p, \boldsymbol{t}), 1 \leqslant \alpha \leqslant M$ depending on a complex variable $p$ and an infinite set of complex time parameters

$$
t:=\left\{t_{A}: A=(\alpha, n) \in A\right\}
$$

where

$$
\boldsymbol{A}=\{(\alpha, 0)\}_{\alpha=2}^{M} \bigcup\{(\alpha, n)\}_{\substack{\alpha=1, \ldots, M \\ n=1, \ldots, \infty}} .
$$

It is assumed that a neighbourhood $\mathcal{D}$ of $\infty$ in the extended complex plane of the $p$ variable exists on which each $z_{\alpha}$ has a simple pole at an associated point $q_{\alpha}=q_{\alpha}(\boldsymbol{t})$. In particular, we set $q_{1}=\infty$ and assume that $z_{1}$ posses the normalized Laurent expansion

$$
\begin{equation*}
z_{1}(p, \boldsymbol{t})=p+\sum_{n=1}^{\infty} \frac{a_{1, n}(\boldsymbol{t})}{p^{n}} \quad p \rightarrow \infty \tag{4}
\end{equation*}
$$

The corresponding expansions for the remaining functions $z_{\alpha}$ at $q_{\alpha}$ will be written as
$z_{i}(p, \boldsymbol{t})=\frac{a_{i,-1}(\boldsymbol{t})}{p-q_{i}(\boldsymbol{t})}+\sum_{n=0}^{\infty} a_{i, n}(\boldsymbol{t})\left(p-q_{i}(\boldsymbol{t})\right)^{n} \quad p \rightarrow q_{i}(\boldsymbol{t}) \quad 2 \leqslant i \leqslant M$.
In order to define the Whitham equations we introduce the system of evolution equations

$$
\begin{equation*}
\frac{\partial z_{\alpha}}{\partial t_{A}}=\left\{\Omega_{A}, z_{\alpha}\right\} \quad 1 \leqslant \alpha \leqslant M \tag{6}
\end{equation*}
$$

Here $\{\cdot, \cdot\}$ is the Poisson bracket

$$
\left\{F_{1}, F_{2}\right\}:=\frac{\partial F_{1}}{\partial p} \frac{\partial F_{2}}{\partial x}-\frac{\partial F_{1}}{\partial x} \frac{\partial F_{2}}{\partial p} \quad x:=t_{1,1}
$$

and the functions $\Omega_{A}=\Omega_{A}(p, t)$ are defined by

$$
\Omega_{A}= \begin{cases}-\ln \left(p-q_{i}(\boldsymbol{t})\right) & \text { for } \quad A=(i, 0) \quad 2 \leqslant i \leqslant M  \tag{7}\\ \left(\left(z_{\alpha}\right)^{n}\right)_{+} & \text {for } \quad A=(\alpha, n) \quad 1 \leqslant \alpha \leqslant M \quad n \geqslant 1\end{cases}
$$

where

$$
\left(\left(z_{\alpha}\right)^{n}\right)_{+}:=P_{(\alpha,+)}\left(z_{\alpha}^{n}\right)
$$

with $P_{(\alpha,+)}$ being the following projectors acting on Laurent series around $p=q_{\alpha}(\boldsymbol{t})$,

$$
\begin{aligned}
& P_{(1,+)}\left(\sum_{n=-\infty}^{\infty} a_{n} p^{n}\right)=\sum_{n=0}^{\infty} a_{n} p^{n} \\
& P_{(i,+)}\left(\sum_{n=-\infty}^{\infty} b_{n}\left(p-q_{i}(\boldsymbol{t})\right)^{n}\right)=\sum_{n=1}^{\infty} \frac{b_{-n}}{\left(p-q_{i}(\boldsymbol{t})\right)^{n}} \quad 2 \leqslant i \leqslant M .
\end{aligned}
$$

The Whitham hierarchy is the set of equations

$$
\begin{equation*}
\frac{\partial \Omega_{A}}{\partial t_{B}}-\frac{\partial \Omega_{B}}{\partial t_{A}}+\left\{\Omega_{A}, \Omega_{B}\right\}=0 \quad A, B \in \boldsymbol{A} \tag{8}
\end{equation*}
$$

which describe the compatibility conditions for the system (6). For $M=1$ the Whitham hierarchy becomes the dispersionless Kadomtsev-Petviasvhili (dKP) hierarchy. Some interesting nonlinear models included in the case $M=2$ are, for example, as follows:
(1) The dispersionless Toda (dT) equation (heavenly equation or Boyer-Finley equation)

$$
\begin{equation*}
\Phi_{x y}+\left(\mathrm{e}^{\Phi}\right)_{t t}=0 \tag{9}
\end{equation*}
$$

which is obtained from (8) by setting $A=(2,0), B=(2,1)$ and

$$
\begin{align*}
& y:=t_{(2,1)} \quad t:=-t_{(2,0)} \\
& \Phi:=\ln a_{2,-1}  \tag{10}\\
& \Omega_{(2,0)}=-\ln \left(p-q_{2}\right) \quad \Omega_{(2,1)}=\frac{a_{2,-1}(t)}{p-q_{2}(t)} .
\end{align*}
$$

(2) The generalized Benney system (generalized gas equation) [10]

$$
\begin{equation*}
a_{t}+(a v)_{x}=0 \quad v_{t}+v v_{x}+w_{x}=0 \quad w_{y}+a_{x}=0 \tag{11}
\end{equation*}
$$

can be regarded as a two-dimensional generalization of the equations for one-dimensional gas dynamics. It takes the form (8) by setting $A=(2,1), B=(1,2)$ and

$$
\begin{array}{ll}
y:=t_{(2,1)} & t:=-\frac{1}{2} t_{(1,2)} \quad a:=a_{2,-1} \quad v:=q_{2} \\
w:=a_{1,1} & \Omega_{(2,1)}=\frac{a_{2,-1}(\boldsymbol{t})}{p-q_{2}(\boldsymbol{t})} \quad \Omega_{(1,2)}=p^{2}+2 a_{1,1} . \tag{12}
\end{array}
$$

## 3. Reductions of the Whitham hierarchy

### 3.1. The S-function

In this paper we shall study algebraic orbits of the zero genus Whitham hierarchy [8]. In other words, we will assume a set of functional relations of the form

$$
\begin{equation*}
z_{i}=f_{i}(z) \quad z:=z_{1} \quad 2 \leqslant i \leqslant M \tag{13}
\end{equation*}
$$

which are easily checked to be compatible with (6).

Furthermore, it follows from (6) and (8) that

$$
\frac{\partial}{\partial t_{B}} \Omega_{A}(p(z, t), t)=\frac{\partial}{\partial t_{A}} \Omega_{B}(p(z, t), t)
$$

and therefore there exists a potential function $S=S(z, t)$ satisfying

$$
\begin{equation*}
\frac{\partial S(z, \boldsymbol{t})}{\partial t_{A}}=\Omega_{A}(p(z, t), \boldsymbol{t}) \quad A \in \boldsymbol{A} \tag{14}
\end{equation*}
$$

Reciprocally, we can state the following proposition on which our solution method for the Whitham hierarchy will be based:

Proposition 1. Let $\left\{z_{\alpha}(p, t)\right\}_{\alpha=1}^{M}$ be a set of functions satisfying a system of time-independent relations (13) as well as (4) and (5). If a function $S(z, t)$ verifying (14) exists, then the functions $z_{\alpha}(p, t)$ provide a solution of the Whitham hierarchy.

Proof. First we note that by setting $A=(1,1)$ in (14) it follows that

$$
p(z, \boldsymbol{t})=\frac{\partial S(z, \boldsymbol{t})}{\partial x}
$$

so that

$$
\begin{aligned}
\frac{\partial p}{\partial t_{A}} & =\frac{\partial}{\partial x} \frac{\partial S(z, \boldsymbol{t})}{\partial t_{A}}=\frac{\partial}{\partial x} \Omega_{A}(p(z, \boldsymbol{t}), \boldsymbol{t}) \\
& =\frac{\partial \Omega_{A}}{\partial p} \frac{\partial p}{\partial x}+\frac{\partial \Omega_{A}}{\partial x}
\end{aligned}
$$

Hence, the function $z=z(p, t)$ satisfies

$$
\begin{aligned}
\frac{\partial z}{\partial t_{A}} & =-\frac{\partial z}{\partial p} \frac{\partial p}{\partial t_{A}}=-\frac{\partial z}{\partial p}\left(\frac{\partial \Omega_{A}}{\partial p} \frac{\partial p}{\partial x}+\frac{\partial \Omega_{A}}{\partial x}\right) \\
& =\frac{\partial \Omega_{A}}{\partial p} \frac{\partial z}{\partial x}-\frac{\partial \Omega_{A}}{\partial x} \frac{\partial z}{\partial p}=\left\{\Omega_{A}, z\right\}
\end{aligned}
$$

Therefore, by using (13) we deduce (6).

## 3.2. $N$-reductions of the Whitham hierarchy

We describe a method for finding solutions of the Whitham hierarchy from functions $z=z(p, \boldsymbol{u})$ depending on $p$ and a finite set of variables $\boldsymbol{u}:=\left(u_{1}, \ldots, u_{N}\right)$, such that the inverse function $p=p(z, \boldsymbol{u})$ satisfies a system of equations of the form

$$
\begin{equation*}
\frac{\partial p}{\partial u_{i}}=R_{i}(p, \boldsymbol{u}) \quad 1 \leqslant i \leqslant N \tag{15}
\end{equation*}
$$

or, equivalently, in terms of $z=z(p, \boldsymbol{u})$

$$
\begin{equation*}
\frac{\partial z}{\partial u_{i}}+R_{i}(p, u) \frac{\partial z}{\partial p}=0 \quad 1 \leqslant i \leqslant N \tag{16}
\end{equation*}
$$

The following conditions for the functions $R_{i}$ will be assumed:
(i) The functions $R_{i}$ are rational functions of $p$ which have singularities only at $N$ simple poles $p_{i}=p_{i}(\boldsymbol{u}), i=1, \ldots, N$, and vanish at $p=\infty$. Therefore, they can be expanded as

$$
\begin{equation*}
R_{i}(p, \boldsymbol{u})=\sum_{j=1}^{N} \frac{r_{i j}(\boldsymbol{u})}{p-p_{j}(\boldsymbol{u})} \tag{17}
\end{equation*}
$$

(ii) The functions $r_{i j}(\boldsymbol{u}), p_{i}(\boldsymbol{u})$ satisfy the compatibility conditions for (16) and (15),

$$
\begin{align*}
& r_{i k} \frac{\partial p_{k}}{\partial u_{j}}-r_{j k} \frac{\partial p_{k}}{\partial u_{i}}=\sum_{l \neq k} \frac{r_{j l} r_{i k}-r_{i l} r_{j k}}{p_{k}-p_{l}} \\
& \frac{\partial r_{i k}}{\partial u_{j}}-\frac{\partial r_{j k}}{\partial u_{i}}=2 \sum_{l \neq k} \frac{r_{j k} r_{i l}-r_{i k} r_{j l}}{\left(p_{k}-p_{l}\right)^{2}} \tag{18}
\end{align*}
$$

where $i \neq j$.
The starting point of the method is a solution $z=z(p, \boldsymbol{u})$ of (15) with a Laurent expansion

$$
\begin{equation*}
z(p, \boldsymbol{u})=p+\sum_{n=1}^{\infty} \frac{a_{n}(\boldsymbol{u})}{p^{n}} \quad p \rightarrow \infty \tag{19}
\end{equation*}
$$

which is assumed to define a univalent analytic function $z: \mathcal{D} \rightarrow \mathcal{D}^{\prime}$ between two neighbourhoods $\mathcal{D}$ and $\mathcal{D}^{\prime}$ of $\infty$ in the extended complex planes of the variables $p$ and $z$ respectively. The next step is to take $(M-1)$ different points $z_{0, i} \in \mathcal{D}^{\prime}, 2 \leqslant i \leqslant M$ and define the functions

$$
\begin{align*}
& z_{1}(p, \boldsymbol{u}):=z(p, \boldsymbol{u}) \\
& z_{i}(p, \boldsymbol{u}):=\frac{1}{z(p, u)-z_{0, i}} \quad 2 \leqslant i \leqslant M . \tag{20}
\end{align*}
$$

Obviously, they satisfy the system of equations

$$
\begin{equation*}
\frac{\partial z_{\alpha}}{\partial u_{i}}+R_{i}(p, \boldsymbol{u}) \frac{\partial z_{\alpha}}{\partial p}=0 \quad 1 \leqslant \alpha \leqslant M \tag{21}
\end{equation*}
$$

and admit expansions of the form

$$
\begin{align*}
& z_{1}(p, \boldsymbol{u})=p+\sum_{n=1}^{\infty} \frac{a_{1, n}(\boldsymbol{u})}{p^{n}} \quad p \rightarrow \infty  \tag{22}\\
& z_{i}(p, \boldsymbol{u})=\frac{a_{i,-1}(\boldsymbol{u})}{p-q_{i}(\boldsymbol{u})}+\sum_{n=0}^{\infty} a_{i, n}(\boldsymbol{u})\left(p-q_{i}(\boldsymbol{u})\right)^{n} \quad p \rightarrow q_{i}(\boldsymbol{u})
\end{align*}
$$

for $2 \leqslant i \leqslant M$, here

$$
\begin{equation*}
q_{i}(\boldsymbol{u}):=p\left(z_{0, i}, \boldsymbol{u}\right) . \tag{23}
\end{equation*}
$$

Observe that introducing the expansions at $p=\infty, q_{i}, i=2, \ldots, M$, of (22) in (21) we obtain

$$
\begin{align*}
& \left\{\begin{array}{l}
\frac{\partial a_{1,1}}{\partial u_{i}}=-\sum_{j=1}^{N} r_{i j} \\
\frac{\partial a_{1,2}}{\partial u_{i}}=-\sum_{j=1}^{N} r_{i j} p_{j} \\
\frac{\partial\left(a_{1,3}+a_{1,1}^{2} / 2\right)}{\partial u_{i}}=-\sum_{j=1}^{N} r_{i j} p_{j}^{2}
\end{array}\right.  \tag{24}\\
& \left\{\begin{array}{l}
\frac{\partial q_{\alpha}}{\partial u_{j}}=R_{j}\left(q_{\alpha}\right) \\
\frac{\partial \log a_{\alpha,-1}}{\partial u_{j}}=\frac{\mathrm{d} R_{j}}{\mathrm{~d} p}\left(q_{\alpha}\right) \quad \text { for } \quad \alpha=2, \ldots, M
\end{array}\right. \tag{25}
\end{align*}
$$

while the other coefficients $a_{\alpha, n}$ in the expansion of $z_{\alpha}$ are determined by

$$
\begin{aligned}
& \frac{\partial a_{1, n}}{\partial u_{j}}=-R_{j, n}+\sum_{k=1}^{n-2}(n-k) R_{j, k} a_{i, n-k} \\
& \frac{\partial a_{i, n}}{\partial u_{j}}=\sum_{k=1}^{n+2} \frac{1}{k!} \frac{\mathrm{d}^{k} R_{j}}{\mathrm{~d} p^{k}}\left(q_{i}\right) a_{i, n-k+1} \quad \text { for } \quad i=2, \ldots, M
\end{aligned}
$$

with

$$
R_{j, k}=\sum_{i=1}^{N} r_{j i} p_{i}^{k-1}
$$

Finally, we introduce the function

$$
\begin{equation*}
\mathcal{S}(p, \boldsymbol{u}, \boldsymbol{t})=\mathcal{S}_{+}(p, \boldsymbol{u}, \boldsymbol{t})+\mathcal{S}_{-}(p, \boldsymbol{u}) \quad \mathcal{S}_{+}:=\sum_{A \in \boldsymbol{A}} t_{A} \Omega_{A}(p, \boldsymbol{u}) \tag{26}
\end{equation*}
$$

where $\Omega_{A}(p, \boldsymbol{u})$ are defined by (7) and (22), and $\mathcal{S}_{-}(p, \boldsymbol{u})$ is an analytic function on $\mathcal{D}$ such that

$$
\begin{equation*}
\lim _{p \rightarrow \infty} \mathcal{S}_{-}(p, \boldsymbol{u})=0 \tag{27}
\end{equation*}
$$

We can now enounce the following statement:
Proposition 2. If $\mathcal{S}_{-}(p, \boldsymbol{u})$ satisfies a system of equations

$$
\begin{equation*}
\frac{\partial \mathcal{S}_{-}}{\partial u_{i}}+R_{i} \frac{\partial \mathcal{S}_{-}}{\partial p}=\sum_{k} \frac{r_{i k} F_{k}}{p-p_{k}} \quad 1 \leqslant i \leqslant N \tag{28}
\end{equation*}
$$

for a given set of functions $\left\{F_{i}=F_{i}(\boldsymbol{u})\right\}_{i=1}^{N}$ verifying the compatibility conditions for (28)

$$
\begin{equation*}
r_{i k} \frac{\partial F_{k}}{\partial u_{j}}-r_{j k} \frac{\partial F_{k}}{\partial u_{i}}=\sum_{l \neq k} \frac{r_{j l} r_{i k}-r_{i l} r_{j k}}{\left(p_{k}-p_{l}\right)^{2}}\left(F_{k}-F_{l}\right) \quad i \neq j \tag{29}
\end{equation*}
$$

and the functions $\left\{u_{i}=u_{i}(t)\right\}_{i=1}^{N}$ are implicitly determined by means of the hodograph relations

$$
\begin{equation*}
\sum_{A \in A} t_{A} \frac{\partial \Omega_{A}}{\partial p}\left(p_{i}(\boldsymbol{u}), \boldsymbol{u}\right)+F_{i}(\boldsymbol{u})=0 \quad 1 \leqslant i \leqslant N \tag{30}
\end{equation*}
$$

then

$$
\begin{equation*}
S(z, \boldsymbol{t}):=\mathcal{S}(p(z, \boldsymbol{u}(\boldsymbol{t})), \boldsymbol{u}(\boldsymbol{t}), \boldsymbol{t}) \tag{31}
\end{equation*}
$$

is an S-function for the Whitham hierarchy.
Proof. The proof is based on the following consequence of (26) and (31),

$$
\begin{equation*}
\frac{\partial}{\partial t_{A}} S(z, \boldsymbol{t})=\Omega_{A}(p(z, \boldsymbol{u}(\boldsymbol{t})), \boldsymbol{t})+\left.\sum_{i=1}^{N} \frac{\partial u_{i}}{\partial t_{A}}\left(\frac{\partial}{\partial u_{i}} \mathcal{S}(p(z, \boldsymbol{u}), \boldsymbol{u}, \boldsymbol{t})\right)\right|_{\boldsymbol{u}=\boldsymbol{u}(t)} \tag{32}
\end{equation*}
$$

and our aim is to prove that under the hypothesis of the proposition the functions

$$
\begin{equation*}
\frac{\partial}{\partial u_{i}} \mathcal{S}(p(z, \boldsymbol{u}), \boldsymbol{u}, \boldsymbol{t})=\frac{\partial \mathcal{S}}{\partial p} R_{i}+\frac{\partial \mathcal{S}}{\partial u_{i}} \tag{33}
\end{equation*}
$$

vanish identically, so that $S(z, t)$ satisfies (14) and, consequently, the statement will follow at once.

By construction the functions (33) are analytic on $\mathcal{D}$ up to a set of possible isolated singularities at $\left\{p_{i}(\boldsymbol{u}), q_{\alpha}(\boldsymbol{u})\right\}$. On the other hand, we observe that (28) implies

$$
\begin{equation*}
F_{i}(\boldsymbol{u})=\frac{\partial \mathcal{S}_{-}}{\partial p}\left(p_{i}(\boldsymbol{u}), \boldsymbol{u}\right) \tag{34}
\end{equation*}
$$

so that (30) is equivalent to

$$
\begin{equation*}
\frac{\partial \mathcal{S}}{\partial p}\left(p_{i}(\boldsymbol{u}), \boldsymbol{u}\right)=0 \quad 1 \leqslant i \leqslant N \tag{35}
\end{equation*}
$$

As a consequence we deduce that the functions (33) are analytic at $p_{i}(\boldsymbol{u})$. Hence, their possible singularities reduce to the points $q_{\alpha}(\boldsymbol{u})$. However, we have

$$
\begin{equation*}
\frac{\partial}{\partial u_{i}} \mathcal{S}(p(z, \boldsymbol{u}), \boldsymbol{u}, \boldsymbol{t})=\sum_{A \in A} t_{A} \frac{\partial}{\partial u_{i}} \Omega_{A}(p(\boldsymbol{u}), \boldsymbol{u})+\frac{\partial \mathcal{S}_{-}}{\partial u_{i}} \tag{36}
\end{equation*}
$$

and we may rewrite

$$
\begin{array}{ll}
\Omega_{(i, 0)}=\ln \frac{1}{z-z_{0, i}}-P_{(i,-)}\left(\Omega_{(i, 0)}-\frac{1}{z-z_{0, i}}\right) & 2 \leqslant i \leqslant M  \tag{37}\\
\Omega_{(\alpha, n)}=z_{\alpha}^{n}-P_{(\alpha,-)}\left(\Omega_{(\alpha, n)}-z_{\alpha}^{n}\right) \quad n \geqslant 1 &
\end{array}
$$

where $P_{(\alpha,-)}:=1-P_{(\alpha,+)}$ are the projectors that annihilate the singular terms of Laurent expansions at $p=q_{\alpha}(\boldsymbol{u})$. Thus, by noting that the first terms on the right-hand side of (37) are $\boldsymbol{u}$-independent while the second terms are analytic at $q_{\alpha}(\boldsymbol{u})$, we conclude that the functions (33) are also analytic at the points $q_{\alpha}(\boldsymbol{u})$. Hence, these functions are analytic on the whole domain $\mathcal{D}$. Moreover, by taking (27) into account, it follows that there is an expansion of the form

$$
\begin{equation*}
\frac{\partial}{\partial u_{i}} \mathcal{S}(p(z, \boldsymbol{u}), \boldsymbol{u}, \boldsymbol{t})=\sum_{n=1}^{\infty} \frac{s_{i, n}(\boldsymbol{u}, \boldsymbol{t})}{p^{n}} \tag{38}
\end{equation*}
$$

so that

$$
\begin{aligned}
\frac{\partial}{\partial u_{i}} \mathcal{S}(p(z, \boldsymbol{u}), \boldsymbol{u}, \boldsymbol{t}) & =P_{(1,-)}\left(\frac{\partial}{\partial u_{i}} \mathcal{S}(p(z, \boldsymbol{u}), \boldsymbol{u}, \boldsymbol{t})\right) \\
& =P_{(1,-)}\left(\frac{\partial \mathcal{S}}{\partial p} R_{i}\right)+\frac{\partial \mathcal{S}_{-}}{\partial u_{i}}
\end{aligned}
$$

Let us now denote by $E=E(p, \boldsymbol{u})$ any entire function of $p$ such that

$$
E\left(p_{i}(\boldsymbol{u}), \boldsymbol{u}\right)=F_{i}(\boldsymbol{u}) \quad i=1, \ldots, N
$$

Then, by taking into account that (30) implies

$$
P_{(1,-)}\left(\left(\frac{\partial \mathcal{S}_{+}}{\partial p}+E\right) R_{i}\right)=0
$$

it follows that

$$
\begin{aligned}
\frac{\partial}{\partial u_{i}} \mathcal{S}(p(z, \boldsymbol{u}), \boldsymbol{u}, \boldsymbol{t}) & =P_{(1,-)}\left(\frac{\partial \mathcal{S}_{-}}{\partial p} R_{i}-E R_{i}\right)+\frac{\partial \mathcal{S}_{-}}{\partial u_{i}} \\
& =\frac{\partial \mathcal{S}_{-}}{\partial p} R_{i}+\frac{\partial \mathcal{S}_{-}}{\partial u_{i}}-\sum_{k} \frac{r_{i k} F_{k}}{p-p_{k}} \\
& =0
\end{aligned}
$$

Hence, the statement follows.

### 3.3. Diagonal reductions, symmetric conjugate nets and potentials

In the case of diagonal reductions $r_{i j}=\delta_{i j} r_{i}$,

$$
\begin{equation*}
\frac{\partial p}{\partial u_{i}}=-\frac{r_{i}(\boldsymbol{u})}{p-p_{i}(\boldsymbol{u})} \tag{39}
\end{equation*}
$$

with $i=1, \ldots, N$, the compatibility conditions (18) and (29) reduce to
$\frac{\partial r_{i}}{\partial u_{j}}=2 \frac{r_{i} r_{j}}{\left(p_{j}-p_{i}\right)^{2}} \quad \frac{\partial p_{i}}{\partial u_{j}}=\frac{r_{j}}{p_{j}-p_{i}} \quad \frac{\partial F_{i}}{\partial u_{j}}=r_{j} \frac{F_{j}-F_{i}}{\left(p_{j}-p_{i}\right)^{2}}$
where $i \neq j$. We may extend our observations of [19] by showing that the diagonal reductions of the Whitham hierarchy determine a particular symmetric conjugate net as well as a set of $(M+1)$ Combescure transformed symmetric conjugate nets. In particular, we prove that the coefficients $a_{1,1}, a_{1,2}, a_{1,3}, a_{\alpha,-1}$ and $q_{\alpha}$ are geometrical potentials associated with these Combescure transformed nets.

A conjugate net with curvilinear coordinates $\boldsymbol{u}$ can be described in terms of a set of rotation coefficients $\left\{\beta_{i j}(\boldsymbol{u})\right\}_{i, j=1, \ldots, N}^{i \neq j}$, which satisfy the Darboux equations [22]

$$
\frac{\partial \beta_{i j}}{\partial u_{k}}=\beta_{i k} \beta_{k j}
$$

for any triple of different labels $i, j, k$. The associated Lamé coefficients $\left\{H_{i}(\boldsymbol{u})\right\}_{i=1, \ldots, N}$ are defined by the solutions of the linear system

$$
\frac{\partial H_{i}}{\partial u_{j}}=\beta_{j i} H_{j} .
$$

Under a Combescure transformation a conjugate net transforms into a parallel conjugate net. The rotation coefficients are left invariant but the Lamé coefficients change. The new Lamé coefficients are given by

$$
\tilde{H}_{i}=\sigma_{i} H_{i}
$$

with

$$
\frac{\partial \sigma_{i}}{\partial u_{j}}=\beta_{j i} \frac{H_{j}}{H_{i}}\left(\sigma_{j}-\sigma_{i}\right)
$$

A conjugate net is called symmetric iff $\beta_{i j}=\beta_{j i}$. Given any pair of parallel symmetric conjugate nets characterized by $\left\{\beta_{i j}, H_{j}\right\}$ and $\left\{\beta_{i j}, \tilde{H}_{j}\right\}$, respectively, then, it follows that locally there exists a potential function $\rho$ so that $\sigma_{i} H_{i}^{2}=\frac{\partial \rho}{\partial u_{i}}$; to see this just observe that

$$
\frac{\partial H_{i} \tilde{H}_{i}}{\partial u_{j}}=\beta_{i j}\left(H_{i} \tilde{H}_{j}+H_{j} \tilde{H}_{i}\right)
$$

which is a symmetric expression provided $\beta_{i j}=\beta_{j i}$.
Taking $H_{i}:=\sqrt{r_{i}}$ and $\beta_{i j}:=\frac{\sqrt{r_{i} r_{j}}}{\left(p_{i}-p_{j}\right)^{2}}$, as the first equation on (40) is $\frac{\partial H_{i}}{\partial u_{j}}=\beta_{i j} H_{j}$, we can identify $H_{i}$ and $\beta_{i j}$ as the Lamé and rotation coefficients, respectively, of a conjugate net.

The functions $\left.\frac{\mathrm{d} \Omega_{i, n}}{\mathrm{~d} p}\right|_{p=q_{\alpha}}$ determining the hodograph relations are polynomials in

$$
p_{i, \alpha}= \begin{cases}p_{i} & \text { for } \quad j=1 \\ \frac{1}{p_{i}-q_{\alpha}} & \text { for } \quad \alpha=2, \ldots, M\end{cases}
$$

observing that $\beta_{i j} H_{j} / H_{i}=\frac{r_{j}}{\left(p_{i}-p_{j}\right)^{2}}$ it is easy to see that these coefficients determine a set of $M$ Combescure transformations. Then, together with the set of Lamé coefficients $\left\{H_{i}=\sqrt{r_{i}}\right\}_{i=1}^{N}$
we have the $M$ families of Lamé coefficients

$$
\left\{H_{i, \alpha}:=p_{i, \alpha} \sqrt{r}_{i}\right\}_{i=1}^{N} \quad \text { for } \quad \alpha=1, \ldots, M
$$

It also follows that there is another Combescure transformed net with Lamé coefficients given by

$$
\left\{h_{i}:=\sqrt{r_{i}} F_{i}\right\}_{i=1}^{N} .
$$

From (24) and (25) we easily find the potentials for $H_{i} H_{i, j}$ and $H_{i, j}^{2}$ :

$$
\begin{align*}
& H_{i}^{2}=-\frac{\partial a_{1,1}}{\partial u_{i}}  \tag{41}\\
& H_{i} H_{i, \alpha}= \begin{cases}-\frac{\partial a_{1,2}}{\partial u_{i}} & \text { for } \quad \alpha=1 \\
-\frac{\partial q_{\alpha}}{\partial u_{i}} & \text { for } \\
\alpha=2, \ldots, M\end{cases}  \tag{42}\\
& H_{i, \alpha}^{2}= \begin{cases}-\frac{\partial\left(a_{1,3}+a_{1,1}^{2} / 2\right)}{\partial u_{i}} & \text { for } \alpha=1 \\
-\frac{\partial \log a_{\alpha,-1}}{\partial u_{i}} & \text { for } \alpha=2, \ldots, M .\end{cases} \tag{43}
\end{align*}
$$

In this way $a_{1,1}, a_{1,2}, a_{1,3}, a_{\alpha,-1}$ and $q_{\alpha}, \alpha=2, \ldots, M$ acquire a direct geometrical meaning.
Observing that

$$
\beta_{i j}=\frac{\sqrt{r_{i} r_{j}}}{\left(p_{i, \alpha}-p_{j, \alpha}\right)^{2}} p_{i, k \alpha}^{2} p_{j, \alpha}^{2} \quad \text { for } \quad \alpha=2, \ldots, M
$$

we write our original compatibility conditions as follows,

$$
\begin{align*}
& \frac{\partial r_{i}}{\partial u_{j}}=2 \frac{r_{i} r_{j}}{\left(p_{j, \alpha}-p_{i, \alpha}\right)^{2}} p_{i, \alpha}^{2} p_{j, \alpha}^{2} \\
& \frac{\partial p_{i, \alpha}}{\partial u_{j}}=\frac{r_{j}}{p_{j, \alpha}-p_{i, \alpha}} p_{i, \alpha}^{2} p_{j, \alpha}^{2}  \tag{44}\\
& \frac{\partial F_{i}}{\partial u_{j}}=r_{j} \frac{F_{j}-F_{i}}{\left(p_{j, \alpha}-p_{i, \alpha}\right)^{2}} p_{i, \alpha}^{2} p_{j, \alpha}^{2}
\end{align*}
$$

for $\alpha=2, \ldots, M$. This system determines a particular symmetric conjugate net and two Combescure transformations of it. Moreover, if we want to recover the original formulation from these $p_{i, \alpha}$ we only need the potential $q_{\alpha}$ of $p_{i, \alpha} r_{i}$ and then $r_{i}, p_{i}=p_{i, \alpha}^{-1}+q_{\alpha}, \alpha=$ $2, \ldots, M$, will fulfil (40).

From (41)-(43) we easily obtain

$$
\begin{aligned}
& \frac{\partial^{2} a_{1,1}}{\partial u_{i} \partial u_{j}}+\beta_{j i} \sqrt{r_{i}} \sqrt{r_{j}}=0 \\
& \left\{\begin{array}{l}
-\frac{\partial a_{1,2}}{\partial u_{i} \partial u_{j}}+\beta_{j i} \sqrt{r_{i}} \sqrt{r_{j}}\left(p_{i}+p_{j}\right)=0 \\
\frac{\partial^{2} q_{\alpha}}{\partial u_{i} \partial u_{j}}+\beta_{j i} \sqrt{r_{i}} \sqrt{r_{j}}\left(p_{i, \alpha}+p_{j, \alpha}\right)=0 \quad \text { for } \quad \alpha=2, \ldots, M
\end{array}\right. \\
& \left\{\begin{array}{l}
\frac{\partial^{2}\left(a_{1,3}+a_{1,1}^{2} / 2\right)}{\partial u_{i} \partial u_{j}}+2 \beta_{j i} \sqrt{r_{i}} \sqrt{r_{j}} p_{i} p_{j}=0 \\
\frac{\partial^{2} \log a_{\alpha,-1}}{\partial u_{i} \partial u_{j}}+2 \beta_{j i} \sqrt{r_{i}} \sqrt{r_{j}} p_{i, \alpha} p_{j, \alpha}=0 \quad \text { for } \quad \alpha=2, \ldots, M .
\end{array}\right.
\end{aligned}
$$

Observe that (40) or (44) can be written in terms of two potentials only. For example, we can choose these potentials to be $q_{\alpha}$ and $\log a_{\alpha,-1}$ and use

$$
r_{i}=-\frac{\left(\frac{\partial q_{\alpha}}{\partial u_{i}}\right)^{2}}{\frac{\partial \log a_{\alpha,-1}}{\partial u_{i}}} \quad p_{i, \alpha}=\frac{\frac{\partial \log a_{\alpha,-1}}{\partial u_{i}}}{\frac{\partial q_{\alpha}}{\partial u_{i}}}
$$

together with

$$
\begin{aligned}
\beta_{i j} \sqrt{r_{i}} \sqrt{r_{j}} & =\frac{r_{i} r_{j}}{\left(p_{i, \alpha}-p_{j, \alpha}\right)^{2}} p_{i, \alpha}^{2} p_{j, \alpha}^{2} \\
& =\frac{\partial \log a_{\alpha,-1}}{\partial u_{i}} \frac{\partial \log a_{\alpha,-1}}{\partial u_{j}}\left(\frac{\partial q_{\alpha}}{\partial u_{i}} \frac{\partial q_{\alpha}}{\partial u_{j}}\right)^{2} \frac{1}{W_{i j}^{-}\left(a_{\alpha,-1}, q_{\alpha}\right)^{2}}
\end{aligned}
$$

where
$W_{i j}^{ \pm}(f, g):=\frac{\partial f}{\partial u_{i}} \frac{\partial g}{\partial u_{j}} \pm \frac{\partial a}{\partial u_{j}} \frac{\partial g}{\partial u_{j}} \quad$ for $\quad \alpha=2, \ldots, M$
$W_{i j}^{-}\left(a_{\alpha,-1}, q_{\alpha}\right)^{2} \frac{\partial^{2} q_{\alpha}}{\partial u_{i} \partial u_{j}}+\frac{\partial \log a_{\alpha,-1}}{\partial u_{i}} \frac{\partial \log a_{\alpha,-1}}{\partial u_{j}} \frac{\partial q_{\alpha}}{\partial u_{i}} \frac{\partial q_{\alpha}}{\partial u_{j}} W_{i j}^{+}\left(a_{\alpha,-1}, q_{\alpha}\right)=0$
$W_{i j}^{-}\left(a_{\alpha,-1}, q_{\alpha}\right)^{2} \frac{\partial^{2} \log a_{\alpha,-1}}{\partial u_{i} \partial u_{j}}+2\left(\frac{\partial \log a_{\alpha,-1}}{\partial u_{i}} \frac{\partial \log a_{\alpha,-1}}{\partial u_{j}}\right)^{2} \frac{\partial q_{\alpha}}{\partial u_{i}} \frac{\partial q_{\alpha}}{\partial u_{j}}=0$

$$
\text { for } i, j=1, \ldots, N \text { and } i \neq j
$$

## 4. Examples

### 4.1. Dispersionless Toda equation

In order to find solutions of the dT equation

$$
\Phi_{x y}+\left(\mathrm{e}^{\Phi}\right)_{t t}=0
$$

we set all $t_{A}$ equal to zero with the exception of $t_{(2,1)}$ and $t_{(2,0)}$, so that from (10) and by denoting

$$
\begin{equation*}
q(\boldsymbol{t}):=q_{2}(\boldsymbol{t}) \quad \nu(\boldsymbol{t}):=a_{2,-1}(\boldsymbol{t}) \tag{45}
\end{equation*}
$$

we have

$$
\begin{equation*}
\Phi=\ln v(\boldsymbol{t}) \tag{46}
\end{equation*}
$$

4.1.1. $N=1$ reductions. Let us first consider reductions $z=z(p, u)$ depending on a single variable $u$ defined by $u=-a_{1,-1}$. Then (15) becomes the Abel equation

$$
\begin{equation*}
\frac{\partial p}{\partial u}=\frac{1}{p-p_{1}(u)} \tag{47}
\end{equation*}
$$

and (30) reads

$$
\begin{equation*}
\frac{t}{p_{1}(u)-q(u)}-\frac{y v(u)}{\left(p_{1}(u)-q(u)\right)^{2}}+x+F(u)=0 \tag{48}
\end{equation*}
$$

where $q(u), p_{1}(u)$ and $F(u)$ are arbitrary functions of $u$. On the other hand,

$$
\frac{\partial q(u)}{\partial u}=\frac{1}{q(u)-p_{1}(u)} \quad \frac{\mathrm{d} \ln v}{\mathrm{~d} u}=-\frac{1}{\left(q(u)-p_{1}(u)\right)^{2}} .
$$

In this way, we may rewrite (48) as

$$
t \sqrt{-\frac{v^{\prime}}{\nu}}-y v^{\prime}-x+F(u)=0
$$

where $v^{\prime}:=\mathrm{d} v / \mathrm{d} u$. Therefore, as $p_{1}(u)$ is an arbitrary function of $u$ we have

$$
\begin{equation*}
t T(u)+y Y(u)+x X(u)+F(u)=0 \quad \Phi=\ln \left(-\frac{X Y}{T^{2}}\right) \tag{49}
\end{equation*}
$$

where $T(u), X(u), Y(u)$ and $F(u)$ are arbitrary functions of $u$. Thus when $T, X, Y$ and $F$ are polynomials up to fourth degree we can obtain explicit solutions. For example, by taking second-order polynomials we obtain
$u:=\gamma \pm \sqrt{\gamma^{2}-\delta} \quad \gamma:=\frac{1}{2} \frac{X_{1} x+Y_{1} y+T_{1} t+F_{1}}{X_{2} x+Y_{2} y+T_{2} t+F_{2}} \quad \delta:=\frac{X_{0} x+Y_{0} y+T_{0} t+F_{0}}{X_{2} x+Y_{2} y+T_{2} t+F_{2}}$
and a solution of dT is

$$
\begin{gathered}
\Phi=\ln \left(\left(X_{1}-\gamma X_{2}\right)\left(-\gamma \pm \sqrt{\gamma^{2}-\delta}\right)+X_{0}-\delta X_{1}\right)+\ln \left(\left(Y_{1}-\gamma Y_{2}\right)\left(-\gamma \pm \sqrt{\gamma^{2}-\delta}\right)\right. \\
\left.+Y_{0}-\delta Y_{1}\right)-2 \ln \left(-\left(T_{1}-\gamma T_{2}\right)\left(-\gamma \pm \sqrt{\gamma^{2}-\delta}\right)-T_{0}+\delta T_{1}\right) .
\end{gathered}
$$

For the choice $T=u^{3}, Y=u^{2}, X=u, F=1$ we obtain the following hodograph relation,

$$
t u^{3}+y u^{2}+x u+1=0
$$

and the corresponding solution of the dispersionless Toda equation is

$$
\Phi=3 \log \left(\frac{6 t f}{12 x t-4 y^{2}+8 y f-f^{2}}\right)
$$

where
$f(x, y, t):=\sqrt[3]{36 x y t-108 t^{2}-8 y^{3}+12 \sqrt{3} t \sqrt{4 x^{3} t-x^{2} y^{2}-18 x y t+27 t^{2}+4 y^{3}}}$.
4.1.2. $N \geqslant 2$ reductions. Let us consider now reductions $z=z(p, \boldsymbol{u})$ involving $N>1$ variables $\boldsymbol{u}:=\left(u_{1}, \ldots, u_{N}\right)$ associated with a system of equations (16) (or (15)). Consequently, the functions $r_{i j}(\boldsymbol{u}), p_{i}(\boldsymbol{u})$ are assumed to satisfy the compatibility conditions (29). In this case we obtain the following system of equations for determining $q(\boldsymbol{u})$ and $\nu(\boldsymbol{u})$,

$$
\begin{equation*}
\frac{\partial q}{\partial u_{i}}=R_{i}(q, \boldsymbol{u}) \quad \frac{\partial \ln v}{\partial u_{i}}=\frac{\partial R_{i}}{\partial p}(q(\boldsymbol{u}), \boldsymbol{u}) \tag{50}
\end{equation*}
$$

where $i=1, \ldots, N$. Thus, the hodograph relations (30) can be written as

$$
\frac{t}{p_{i}(\boldsymbol{u})-q(\boldsymbol{u})}-\frac{y \exp \left(\int^{u} \sum_{j=1}^{N} \frac{\partial R_{j}}{\partial p}(q(\boldsymbol{u}), \boldsymbol{u}) \mathrm{d} u_{j}\right)}{\left(p_{i}(\boldsymbol{u})-q(\boldsymbol{u})\right)^{2}}+x+F_{i}=0
$$

for $i=1, \ldots, N$. In the case of diagonal reductions the function $q$ solves

$$
\frac{\partial q}{\partial u_{i}}=\frac{r_{i}}{p_{i}-q}
$$

and by denoting

$$
P_{i}:=\frac{1}{p_{i}-q}
$$

the hodograph equations read

$$
t P_{i}-y P_{i}^{2} \exp \left(-\int^{u} \sum_{j=1}^{N} r_{j} P_{j}^{2} \mathrm{~d} u_{j}\right)+x+F_{i}=0
$$

For example a simple solution of the compatibility conditions (40) for $N=2$ is

$$
\begin{array}{ll}
r_{1}=-r_{2}=\frac{1}{8}\left(u_{1}-u_{2}\right) & p_{1}=\frac{1}{4}\left(3 u_{1}+u_{2}\right) \\
p_{2}=\frac{1}{4}\left(u_{1}+3 u_{2}\right) & F_{1}=-F_{2}=\frac{c}{u_{2}-u_{1}} \tag{51}
\end{array}
$$

where $c$ is an arbitrary complex constant. In this case we can obtain the explicit solution $z(p, \boldsymbol{u})$ of (16) satisfying (19). It is given by

$$
\begin{equation*}
z=p+\frac{\left(u_{1}-u_{2}\right)^{2}}{16 p-8\left(u_{1}+u_{2}\right)} . \tag{52}
\end{equation*}
$$

Thus, from (23) we can set

$$
\begin{equation*}
q(\boldsymbol{u})=-\frac{1}{2} \sqrt{\left(u_{1}+z_{0}\right)\left(u_{2}+z_{0}\right)}+\frac{1}{4}\left(u_{1}+u_{2}-2 z_{0}\right) \tag{53}
\end{equation*}
$$

so that by denoting

$$
U_{i}:=\sqrt{u_{i}+z_{0}} \quad i=1,2
$$

the hodograph relations become
$x+\frac{4 y}{\left(U_{1} U_{2}\right)^{2}}-\frac{c}{\left(U_{1}-U_{2}\right)^{2}}=0 \quad 4 t+\left(2 x-\frac{c}{\left(U_{1}-U_{2}\right)^{2}}\right)\left(U_{1}+U_{2}\right)^{2}-c=0$
and we have

$$
\begin{equation*}
\Phi=\ln \frac{\left(U_{1}+U_{2}\right)^{2}}{U_{1} U_{2}} \tag{55}
\end{equation*}
$$

The system (54) reduces to a quartic equation. To see this it is enough to write the system (54) as

$$
x+\frac{64 y}{\left(u_{+}-u_{-}\right)^{2}}-\frac{c}{u_{-}}=0 \quad 4 t+\left(2 x-\frac{c}{u_{-}}\right) u_{+}-c=0
$$

where

$$
u_{ \pm}:=\left(U_{1} \pm U_{2}\right)^{2} .
$$

Then by eliminating $u_{+}=(c-4 t)\left(2 x u_{-}-c\right)^{-1} u_{-}$we obtain

$$
\begin{aligned}
& x^{3} u_{-}^{4}+(-3 c+4 t) x^{2} u_{-}^{3}+\left(4 t^{2}-8 c t+3 c^{2}+64 x y\right) x u_{-}^{2} \\
&+\left(-4 t^{2}+4 c t-64 x y-c^{2}\right) c u_{-}+16 c^{2} y=0
\end{aligned}
$$

and the associated solution (55) of the dT equation is given by

$$
\begin{equation*}
\Phi=\log \left(\frac{8 t-2 c}{2 t-c+x u_{-}}\right) . \tag{56}
\end{equation*}
$$

### 4.2. Generalized gas equation

We consider now solutions of the generalized gas equation

$$
\begin{equation*}
a_{t}+(a v)_{x}=0 \quad v_{t}+v v_{x}+w_{x}=0 \quad w_{y}+a_{x}=0 . \tag{57}
\end{equation*}
$$

We set all time variables $t_{A}$ equal to zero except for $t_{(2,1)}$ and $t_{(1,2)}$ and use the notation conventions (45). Then, from (12) it follows that the dependent variables are given by

$$
a=v(\boldsymbol{t}) \quad v=q(\boldsymbol{t}) \quad w=a_{1,1}(\boldsymbol{t}) .
$$

4.2.1. $N=1$ reductions. Reductions $z=z(p, u)$ depending on a single variable $u$, defined by $u=-a_{1,-1}$, lead to the Abel equation (47) and to a hodograph relation (30) of the form

$$
\begin{equation*}
-t p_{1}-\frac{y v(u)}{\left(p_{1}(u)-q(u)\right)^{2}}+x+F(u)=0 \tag{58}
\end{equation*}
$$

where $q(u), p_{1}(u)$ and $F(u)$ are arbitrary functions of $u$. We may rewrite (58) as
$t\left(\frac{1}{P(u)}-\int^{u} P(u) \mathrm{d} u\right)-y P^{2} \exp \left(-\int^{u} P^{2} \mathrm{~d} u\right)+x+F(u)=0$
where $P:=\partial_{u} q(u)$ is an arbitrary function of $u$ and

$$
\begin{equation*}
a=\exp \left(-\int^{u} P^{2} \mathrm{~d} u\right) \quad v=\int^{u} P \mathrm{~d} u \quad w=-u \tag{60}
\end{equation*}
$$

It is convenient to use the following equivalent form of (57):

$$
\begin{equation*}
a_{t}+(a v)_{x}=0 \quad\left(v_{t}+v v_{x}\right)_{y}-a_{x x}=0 \tag{61}
\end{equation*}
$$

To prove the equivalence between (57) and (61) note that given a solution $(a, v)$ of (61), then by integrating the second equation of (61) with respect to the $y$ variable we conclude the existence of a function $f(x, t)$ such that

$$
v_{t}+v v_{x}-\int_{y_{0}}^{y} a_{x x} \mathrm{~d} y+f_{x}(x, t)=0
$$

Then, a solution of (57) is given by $(a, v, w)$ with

$$
w(x, y, t):=f(x, t)-\int_{y_{0}}^{y} a_{x}(x, y, t) \mathrm{d} y .
$$

Now we will show two reformulations of the previous $N=1$ technique providing us with explicit solutions to (61).
(1) If we introduce $a(u)=\exp \left(-\int^{u} P^{2}(u) \mathrm{d} u\right)$ and assume that $a$ is a solution of the following ODE,

$$
\frac{\mathrm{d} a}{\mathrm{~d} u}=-\frac{1}{a f^{\prime}(a)^{2}}
$$

for a given function $f=f(a)\left(f^{\prime}(a)=\frac{\mathrm{d} f}{\mathrm{~d} a}\right)$, then as $\log a=-\int^{u} P^{2}(u) \mathrm{d} u$ we have $1 / P:=-a f^{\prime}(a)$ and we obtain the following hodograph relation,

$$
\begin{equation*}
\left(a f^{\prime}(a)+f(a)\right) a f^{\prime}(a)^{2} t+y-(x+F(a)) a f^{\prime}(a)^{2}=0 . \tag{62}
\end{equation*}
$$

Thus, given two arbitrary functions $f$ and $F$, and a solution $a(x, y, t)$ of (62), it follows that $a, v=f(a)$ provide a solution of (61). For example, if $f=A a+B$ and $F=-\left(C a^{3}+D a^{2}+E a+G\right)$, with $A, B, C, D, E$ and $G$ being arbitrary constants we obtain the hodograph relation

$$
A^{2} C a^{4}+A^{2} D a^{3}+A^{2}(2 A t+E) a^{2}+A^{2}(B t-A x+A G) a+y=0
$$

and the solution of (61) is $a, v$ with $v$ given by

$$
v=A a+B
$$

If we take $f=a+1$ and $F=a^{3}$ we obtain the following solution,

$$
\begin{aligned}
& a=\alpha-\frac{3(t-x)-4 t^{2}}{9 \alpha}-\frac{2 t}{3} \\
& v=a+1
\end{aligned}
$$

with

$$
\begin{gathered}
\alpha:=\left(12 t(t-x)-18 y-\frac{32}{3} t^{3}+2\left(12 t^{3}-36 x t^{2}-12 t^{4}+36 t x^{2}+24 x t^{3}-12 x^{3}\right.\right. \\
\left.\left.-12 x^{2} t^{2}-108 t^{2} y+108 t x y+81 y^{2}+96 y t^{3}\right)^{1 / 2}\right)^{1 / 3} .
\end{gathered}
$$

Another simple example arises for $f(a)=\log a, F=0$, the corresponding solution to the hodograph equation is

$$
a(x, y, t)=\frac{t}{y} W\left(\frac{y}{t} \mathrm{e}^{x / t-1}\right)
$$

and

$$
v(x, y, t)=W\left(\frac{y}{t} \mathrm{e}^{x / t-1}\right)-1+\frac{x}{t}
$$

where $W$ is the Lambert function defined by

$$
W(z) \mathrm{e}^{W(z)}=z
$$

(2) Alternatively, we may introduce the dependent variable $v=\int^{u} P \mathrm{~d} u$ where $v$ is assumed to satisfy the ODE $\frac{\mathrm{d} v}{\mathrm{~d} u}=-g^{\prime}(v) / g(v)$. Then, from (59) and by taking into account that $g$ is the inverse function of $f$, the following hodograph relation is obtained:

$$
-t\left(g(v)+v g^{\prime}(v)\right) g(v)-y g^{\prime}(v)^{3}+g(v) g^{\prime}(v)+F(v)+g(v) g^{\prime}(v)=0
$$

Therefore, given two arbitrary functions $g, F$ and a solution $v(x, y, t)$ to this hodograph relation, we obtain a solution $a, v$ of (61) with $a$ given by

$$
a=g(v)
$$

In particular, if $g:=A \mu^{2}+B \mu+C$ and $F=D \mu+E$ the hodograph relation takes the form

$$
\begin{gathered}
-3 A^{2} t \mu^{4}+\left(2 A^{2} x-8 A^{3} y-5 A B t+A D\right) \mu^{3}+\left(3 A B x-12 A^{2} B y-2\left(2 A C+B^{2}\right) t\right. \\
+A E+B D) \mu^{2}+\left(\left(2 A C+B^{2}\right) x-6 A B^{2} y-3 B C t\right. \\
+B E+C D) \mu+B C x-B^{3} y-C^{2} t+E C=0
\end{gathered}
$$

4.2.2. $N \geqslant 2$ reductions. Reductions $z=z(p, \boldsymbol{u})$ involving $N>1$ variables $\boldsymbol{u}:=\left(u_{1}, \ldots, u_{N}\right)$ can be analysed by the same scheme as in the case of the dT equation. They are associated with a system of equations (16) (or (15)), where the functions $r_{i j}(\boldsymbol{u}), p_{i}(\boldsymbol{u})$ are assumed to verify the compatibility conditions (29). The functions $q(\boldsymbol{u})$ and $\nu(\boldsymbol{u})$ are determined by solving the system (50). The hodograph relations (30) read

$$
\begin{equation*}
-t p_{i}(\boldsymbol{u})-\frac{y \exp \left(\int^{u} \sum_{j=1}^{N} \frac{\partial R_{j}}{\partial p}(q(\boldsymbol{u}), \boldsymbol{u}) \mathrm{d} u_{j}\right)}{\left(p_{i}(\boldsymbol{u})-q(\boldsymbol{u})\right)^{2}}+x+F_{i}=0 \tag{63}
\end{equation*}
$$

where $1 \leqslant i \leqslant N$. The dependent variables of the generalized Benney system are then given by

$$
\begin{align*}
a & =\exp \left(\int^{u} \sum_{j=1}^{N} \frac{\partial R_{j}}{\partial p}(q(\boldsymbol{u}), \boldsymbol{u}) \mathrm{d} u_{j}\right) \quad v=q(\boldsymbol{u})  \tag{64}\\
w & =\int^{u} \sum_{i, j=1}^{N} \operatorname{Res}\left(R_{i}(p, \boldsymbol{u}), p_{j}(\boldsymbol{u})\right) \mathrm{d} u_{j} .
\end{align*}
$$

In the particular case of the $N=2$ reduction of diagonal type defined by

$$
\begin{align*}
& r_{1}=-r_{2}=\frac{1}{8}\left(u_{1}-u_{2}\right) \\
& p_{1}=\frac{1}{4}\left(3 u_{1}+u_{2}\right) \quad p_{2}=\frac{1}{4}\left(u_{1}+3 u_{2}\right) \tag{65}
\end{align*}
$$

the function $q(\boldsymbol{u})$ is given by (53), so that by denoting

$$
U_{i}:=\sqrt{u_{i}+z_{0}} \quad i=1,2
$$

we have

$$
\begin{align*}
& q(\boldsymbol{u})=-\frac{1}{2} U_{1} U_{2}+\frac{1}{4}\left(U_{1}^{2}+U_{2}^{2}-4 z_{0}\right)  \tag{66}\\
& p_{1}(\boldsymbol{u})=\frac{1}{4}\left(3 U_{1}^{2}+U_{2}^{2}-4 z_{0}\right) \quad p_{2}(\boldsymbol{u})=\frac{1}{4}\left(U_{1}^{2}+3 U_{2}^{2}-4 z_{0}\right) .
\end{align*}
$$

The hodograph relations (63) reduce to

$$
\begin{align*}
& -\frac{4 y}{U_{1}^{3} U_{2}}-\frac{1}{4}\left(3 U_{1}^{2}+U_{2}^{2}-4 z_{0}\right) t+x+F_{1}=0  \tag{67}\\
& -\frac{4 y}{U_{2}^{3} U_{1}}-\frac{1}{4}\left(3 U_{2}^{2}+U_{1}^{2}-4 z_{0}\right) t+x+F_{2}=0
\end{align*}
$$

and (64) implies
$a=\frac{\left(U_{1}+U_{2}\right)^{2}}{U_{1} U_{2}} \quad v=\frac{1}{4}\left(U_{1}-U_{2}\right)^{2}-z_{0} \quad w=\frac{1}{16}\left(U_{1}^{2}-U_{2}^{2}\right)^{2}$.
In particular, for $F_{1}=F_{2}=0$ one finds the following explicit solution:
$a=\frac{2}{3} \frac{x+z_{0} t}{\left(t^{2} y\right)^{1 / 3}}+2 \quad v=\frac{x}{3 t}-\left(\frac{y}{t}\right)^{1 / 3}-\frac{2}{3} z_{0} \quad w=\frac{\left(x+z_{0} t\right)^{2}}{9 t^{2}}-\left(\frac{y}{t}\right)^{2 / 3}$.

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